

Code of Practice for the development of Automated Driving Functions

L3Pilot Final Event

Yves Page, Renault On behalf of all co-authors (Yu, Thibault, Felix, Moritz, Frederik, Fabio, Stefan, Andreas, Jorge, Giancarlo, Elias, Michele, Silvia, Qi, Oliver, Adam, Stuart, Johannes, Frank, Ulrich, Roland, Elisabeth)

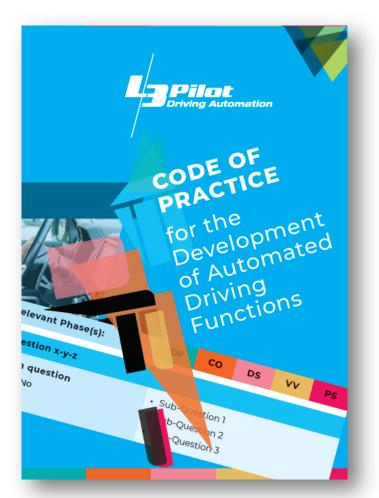
www.L3Pilot.eu

Twitter@_L3Pilot_

LinkedInL3Pilot



Foreword(s)



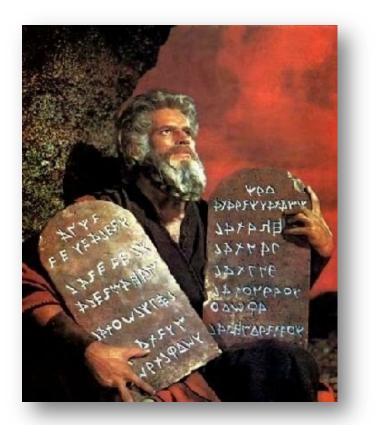


- What do we mean by "Code" ?
- What do we mean by "Code of Practice"?





Foreword(s)



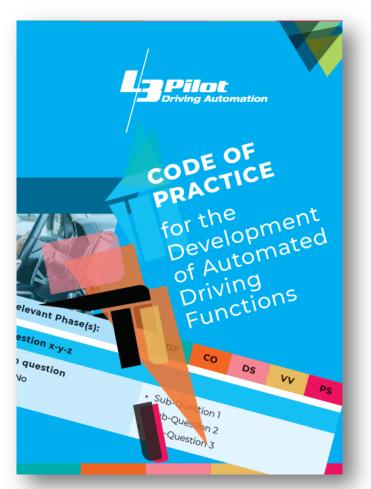
What is a Code?

- A set of rules of behaviour, practices or conventions in society, formalised or not (e.g. dress code)
- A document (book or other) where these rules are written (e.g. mining code)
- An algorithmic rule for converting pieces of data into another form or representation, possibly for confidentiality purposes (e.g. selecting the first letter of each word) the result of applying this rule to an item of information.









What do we mean by "Code" ?

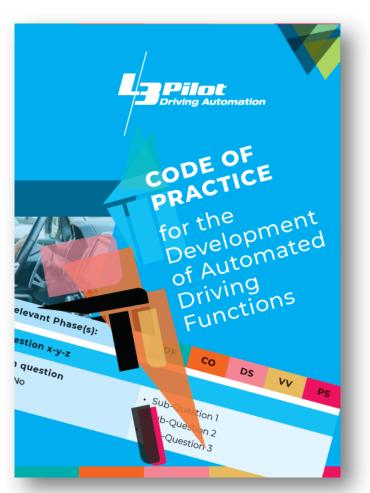
A document (book or other) where **good practices** are written







Foreword(s)



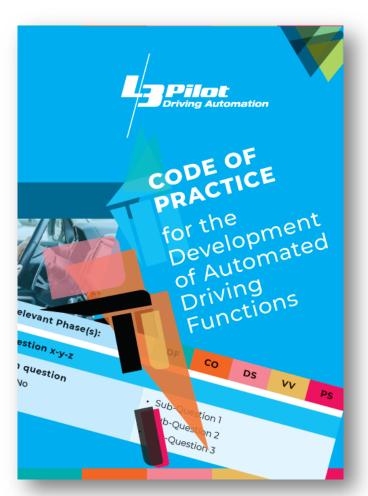
What do we mean by "Code of Practice" ?

The Code of Practice for the Development of Automated Driving Functions provides comprehensive guidelines for supporting the design, development, verification and validation of automated driving technologies.





Foreword(s)



Entrant Protection of Allowed Contract Protection of Allowed Contract Protection

• What do we mean by "Code of Practice" ?



Collection of best practices



Typical process for the development and release of ADF



Safety aspects and methods to confirm a safe operation of ADF

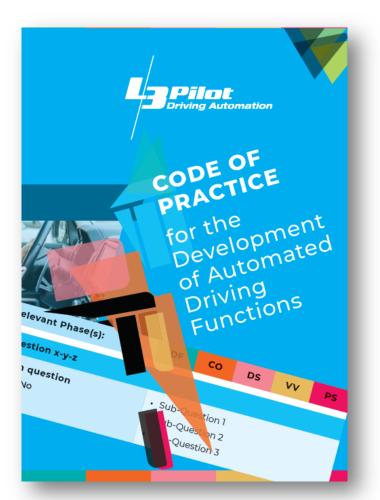


Checklists, references











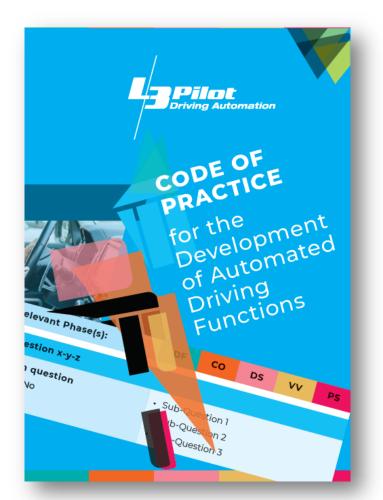
• Do we start from scratch ?













• Who is it for ?





Who is it for ?





Vehicle Manufacturers, Suppliers

Insurance bodies

Public Authorities



Academics

Pilot

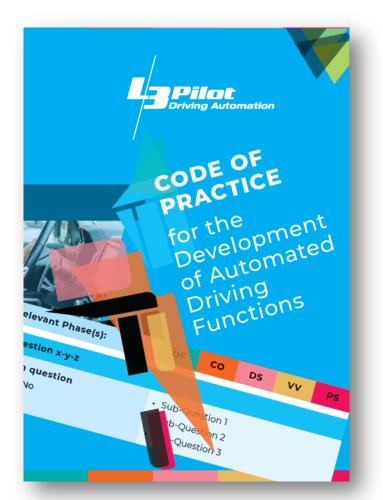
Regulation & Type approval bodies

General Public









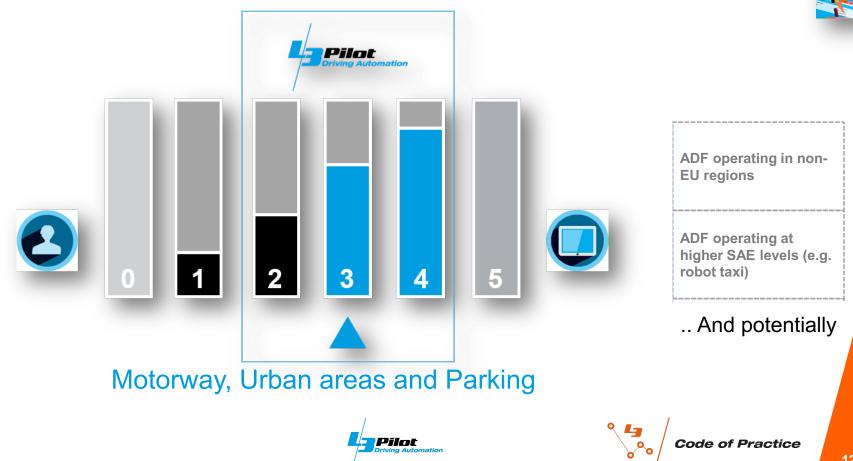


Scope of CoP-ADF

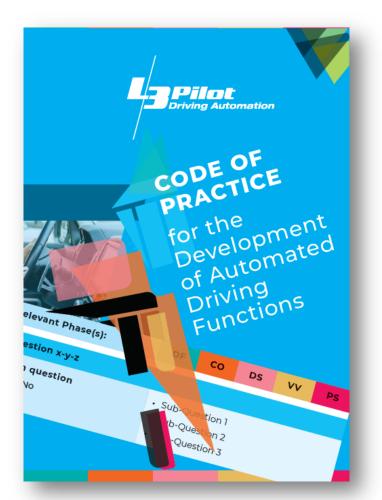




Scope of the CoP-ADF









•What will you find in?





Contents







3 -• 155 Questions (and even more sub-questions)

References to standards





Category	Topics
Overall Guidelines & Overall Guidelines &	 Minimal Risk Manoeuvre Documentation Existing Standards Testing (including Simulation)
ODD Vehicle Level	 Requirements Scenarios and Limitations Performance Criteria and Customer Expectations Architecture
ODD Traffic System & Behavioural Design	 Automated Driving Risks and Coverage of Interaction with Mixed Traffic V2X Interaction Traffic Simulation Ethics & other Traffic related Aspects
Safeguarding Automation	 Functional Safety Cybersecurity Implementation of Updates Safety of the intended Functionality Data Recording, Privacy and Protection
Human-Vehicle Integration	 Guidelines for HVI Mode Awareness, Trust & Misuse Driver Monitoring Controllability & Customer Clinics Driver Training & Variability of Users

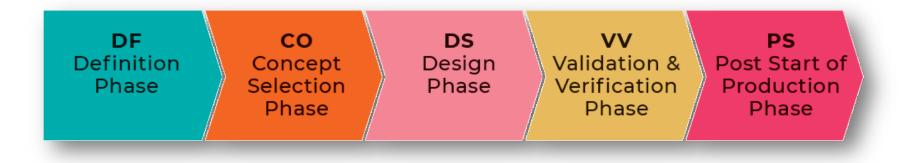
Pilot Driving Automation

Code of Practice

° **L**J ° ° ,

... All over the development process...









Structure of the questions

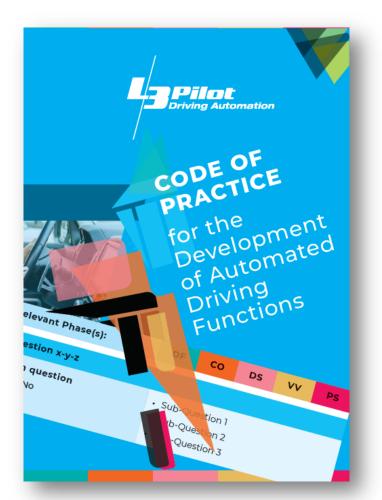


Relevant Phase(s):	DF	со	DS	vv	PS		
Question x-y-z							
Main question Yes / No	 Sub-Question 1 Sub-Question 2 Sub-Question 3 						







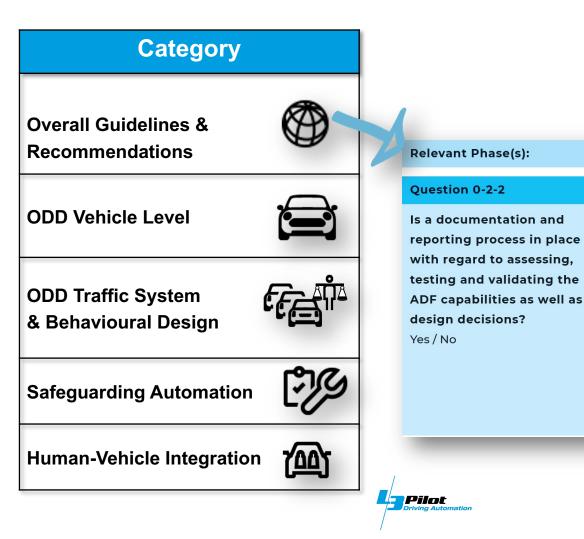




Examples







Topic: Documentation Is a process established to document the performed tests and pass/fail compliance?

DS

VV

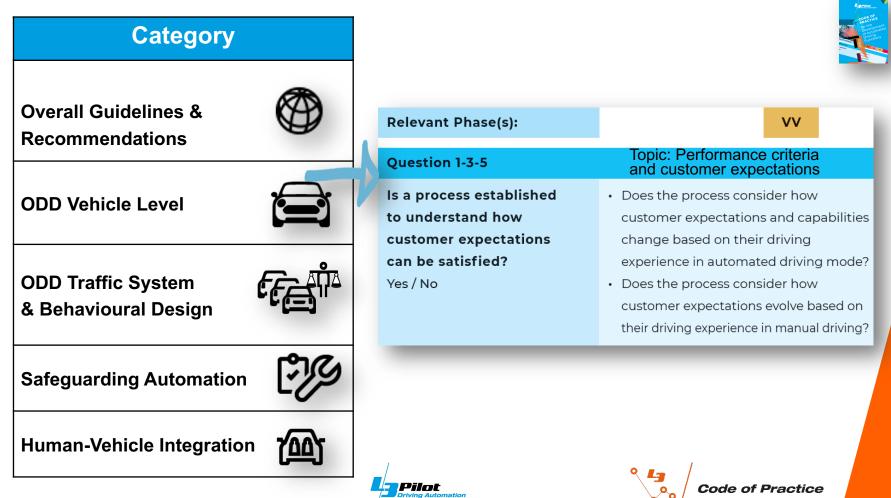
PS

DF

CO

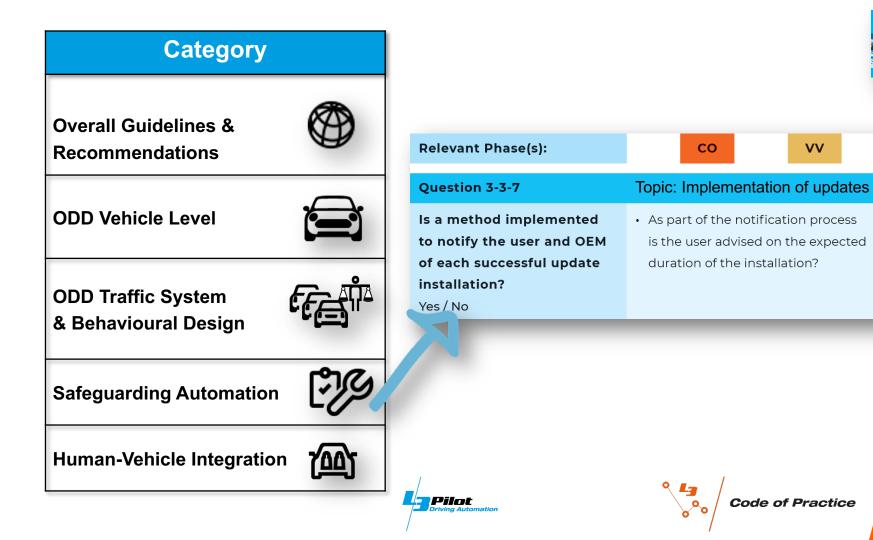
- Is a process established to document updates of the test plan?
- Does the documentation format comply with requirements of external stakeholders?
- Is a safety argumentation (analogous safety case in ISO 26262) set up and described?







Relevant Phase(s):	DF	со	DS	vv	PS		
Question 2-1-1 Topic: Automated driving risks and coverage interaction with mixed traffic							
Are the risks of the ADF • Are the risks at entry to and exit from					t from		
within its ODD considered?	the C	DD cons	idered?				
Yes / No	 Are the risks from infrastructure or other road users considered? Are unspecified or unexpected event 						
	 identified from studies in real traffic? Does the HARA consider unspecified or unexpected events? Are the function limitations within the ODD considered? 						
	 Is the or dis ident Is the 	e recordir sengager ify risks? ere a mec n or shari	ng of ADF ments ut hanism i	ilised to for the p	help ubli-		
		a third pa	-	sengage	inents		





VV

Category

Overall Guidelines & Recommendations



ODD Vehicle Level



ODD Traffic System & Behavioural Design

gn

Safeguarding Automation

Human-Vehicle Integration

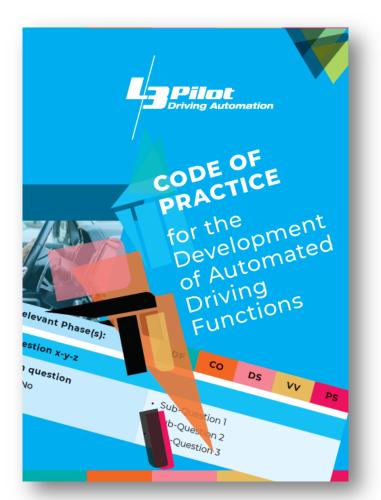




Relevant Phase(s):	со
Question 4-1-2	Topic: Guidelines for HVI
Are unintentional activations and deactivations of the ADF	 Are the ADF controls designed so as to reduce accidental activation.
prevented? Yes / No	 deactivation? Is the ADF able to determine accidental activations / deactivations vs intentional ones? Is a fall-back considered for the case where an accidental deactivation occurs and the driver is not in the
	loop?









References







Pilot

Driving Automation















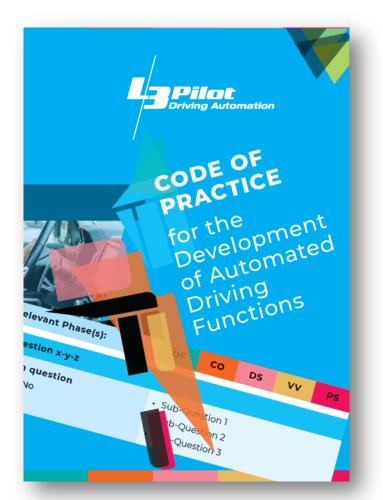




But also, many other ones

	Reference	Relevant topics in CoP-ADF	
Belevant topics in CoP-	DI Fabio, U., Broy, M., Brüngger, R. et al. (2017). "Ethic commission: automated and connected driving", Report of ethics commission appointed by the federal minister of transport and digital infrastructure.	4.3.4 Ethics & Other Traffic- Related Aspects	ance Ranagi vancies – Aurctonal Relevant topics in c
Bonneton, 3-F, Centy, D, Davidinet-vehicles Bonneton, 3-F, Centy, D, Davidinated vehicles and prometed and automated vehicles	ENISA, "ENISA Good practices for Security of Smart Cars", European Union Agency for Cybersecurity (ENISA 2019).	4.4.2 Cybersecurity 4.4.3 Implementation of Updates	all Existing Star
Deference r.et.al. (D00) A (D00)	Flemisch, F., Abbink, D., Itoh, M. et al. (2016). "Shared control is the sharp end of cooperation: Towards a common framework of joint action, shared control and human machine cooperation", 13th IFAC Symposium on Analysis, Design, and Evaluation of Human-Machine Systems HMS 2016.	4.23 Performance Criteria and Customer Expectations	Leasted Japento 431 Indexensitation of Updates Underson and sources 143 Indexensitation of Updates Underson and sources 144 Safety of the Indexensitation 150 Safety 150 Safety 15
Prusquer = +6 System = Interior + Ffects = + thesis No.	Ford (2018), "A matter of trust – Ford's approach to developing self-driving vehicles", Ford safety report.	4.5.2 Mode Awareness, Trust & Misuse 4.5.5 Driver Training & Variability of Users	SI Sijstem and Software Updates Updates
ADD regime BPA Dispective Control (UNAPP) softems' Dispective Control (Control (Con	Forster, Y., Hergeth, S., Naujoks, F., Krems, J. F., & Keinath, A. (2019). Empirical Validation of a Checklist for Heuristic Evaluation of Automated Vehicle HMIs. In International Conference on Applied Human Factors and Ergonomics (pp. 3-14). Springer, Cham.	4.5.1 Guidelines for HVI	States and schware security of the schware states and schware security of the schware schware states and schware schware schware schware schware schware schware schware schware schware schware schware schware schware schware schware schware schware schware
ACEA 2007, ACEA Report C/Sersecury, ACEA Report C/Sersecury, ACEA Report U/OpenDrue (2020) (https://www.asam.net/ - usersentel) - usersentel) - usersentel - userse	Fridman, L, Brown, D. E, Glazer, M, Angell, W, Spencer, D. et al. (2019) MIT Advanced Vehicle Technology Study: Large-Scale Naturalistic Driving Study of Driver Behavior and Interaction with Automation. IEEE Access, vol. 7, pp. 102021-102038.	4.5.3 Driver Monitoring	und sources and the source of
ASM OpenDisalippendities. Sand and Deal (Section 1997). SAM OpenService (SGD), (https://www.seam.net/) Sand and Standing (SGD), (https://www.seam.net/) Sand and Standing (SGD), (https://www.seam.net/) SAM JL Standing (SGD), (https://www.seam.net/) Sand and Standing (SGD), (https://www.seam	Gellerman, H., Svanberg, E., Kotiranta, R., Heinig, I., et al. (2017). "Data sharing framework", FOT-Net Deliverable D3.1. General Motors (2018). "2018 self-driving safety	4.4.5 Data Recording, Privacy and Protection 4.5.2 Mode Awareness, Trust &	444 Solety of the Interder Safety of the Interder Safety of the Interder Safety of the Interder
Summary Creen, N., and Market M. 2019. System Colling Juposted USSA. Colling Juposted USSA. Coll Numerimediate Market	report", GM safety report.	Misuse 4.5.5 Driver Training & Variability of Users	4-31 Automated Drives
Dimitelia A. Eberley, U.S. Marketter, D.S. St. detaration and Globalary, Addights St. detaration and Globalary, Addights St.	48 Dual of the second sec		And Counting Datas Many Transfer of Interaction with a fit of the
dent		/	"retoring.
	_	Pilot Driving Automation	Code of Practic





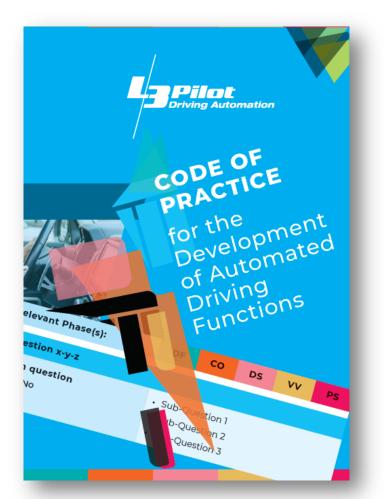


Afterword





Afterword



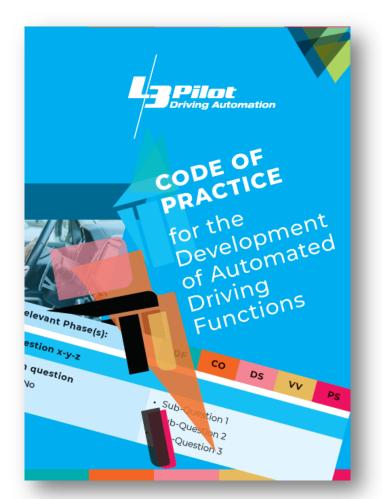


- Scope of the CoP-ADF is not to provide technical solutions, but to support the development of ADF by ensuring that relevant aspects have been considered.
- The purpose of the questions is to make the developers and other relevant stakeholders aware of certain aspects and to ensure that reasons for decisions are taken and documented.





Last words



Contraction Contra

- No single approach for the implementation of safe ADF
- Neutrality in terms of technology
- This CoP-ADF presents a trade-off between detailed information and broad understanding
- Automated driving is a rapidly evolving technology: state-of-the-art needs to be continuously updated







Twitter@ L3Pilot

Thank you for your kind attention.

Yves Page Renault yves.page@renault.com



This project has received funding from the European Union's Horizon 2020 research and innovation programme under grant agreement No 723051.

LinkedInL3Pilot

www.L3Pilot.eu