



# Piloting Automated Driving on European Roads

Automated Vehicle Symposium

Orlando, 16 July 2019

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**L3 Pilot**  
*Driving Automation*

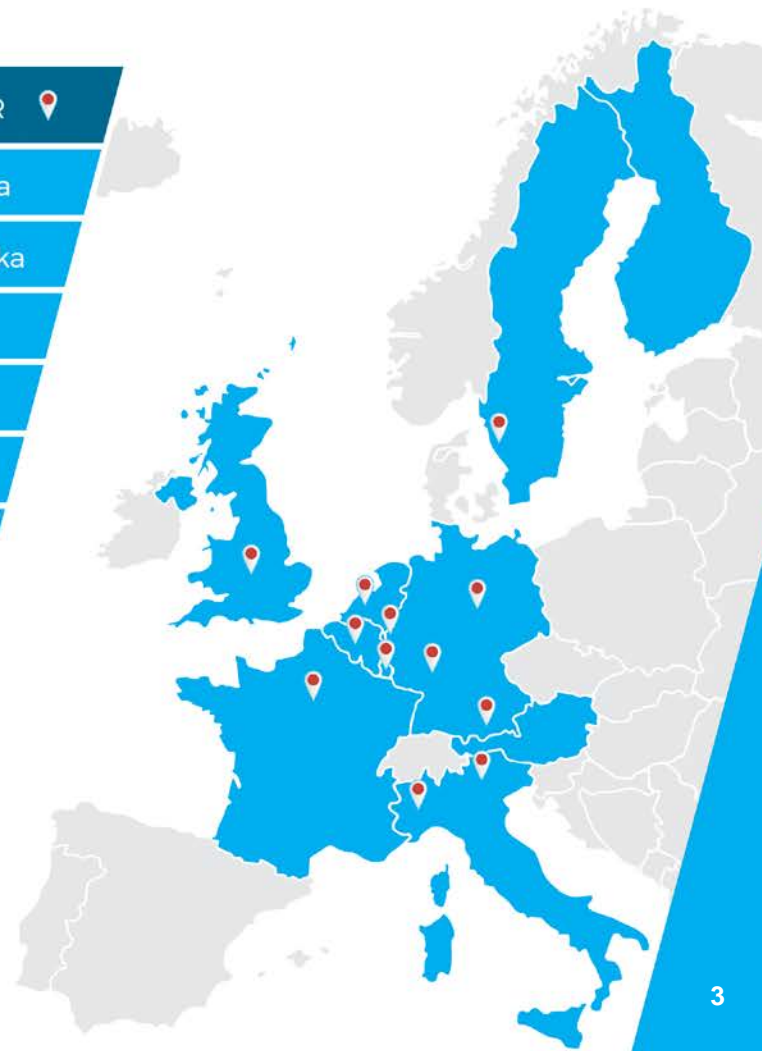
**1,000**  
drivers

**100**  
cars

**10**  
countries

# Pilot across Europe

COUNTRY / REGION / PARTNER 	
BE / Brussels	Toyota
DE / Aachen	Ford / ika
DE / Munich	BMW
DE / Offenbach	Honda
DE / Wolfsburg	VW
DE / Ingolstadt	Audi
FR / Paris and other regions	REN / PSA
IT / Turin and Trento	CRF
LU / NL	Aptiv
SE / Gothenburg	Volvo
UK / Coventry	JLR
+ Cross-border activities	



# Facts



This project has received funding from the European Union's Horizon 2020 research and innovation programme under grant agreement No 723051.



**€68** million BUDGET


















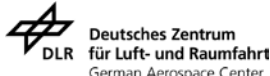












**48** months DURATION, starting in September 2017

**€36** million FUNDING

**34** PARTNERS, among them OEMs, suppliers, research, SMEs, insurers, authorities and user groups

**12** COUNTRIES involved: Austria, Belgium, France, Finland, Germany, Greece, Italy, Netherlands, Norway, Sweden, Switzerland, UK

# Partners

OEMs	      	       	
Suppliers	  	   	
SMEs	 	       	
Insurers	 		

1,000 drivers 100 cars 10 European countries Piloting Automated Driving on European Roads.

Methodology



Data



Evaluation



Fleet



Piloting



PREPARE

DRIVE

EVALUATE



TRAFFIC JAM CHAUFFEUR



MOTORWAY CHAUFFEUR

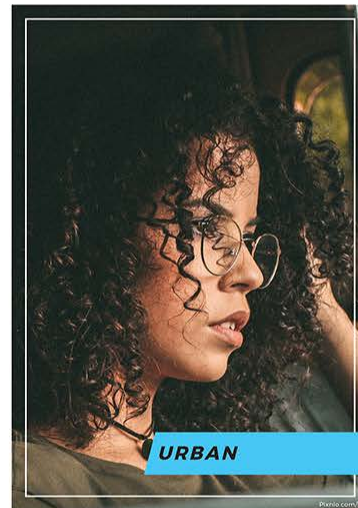
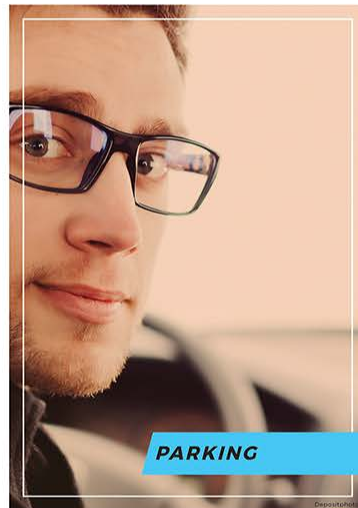


PARKING CHAUFFEUR



URBAN CHAUFFEUR

**L3 Pilot**  
Driving Automation  
Applications

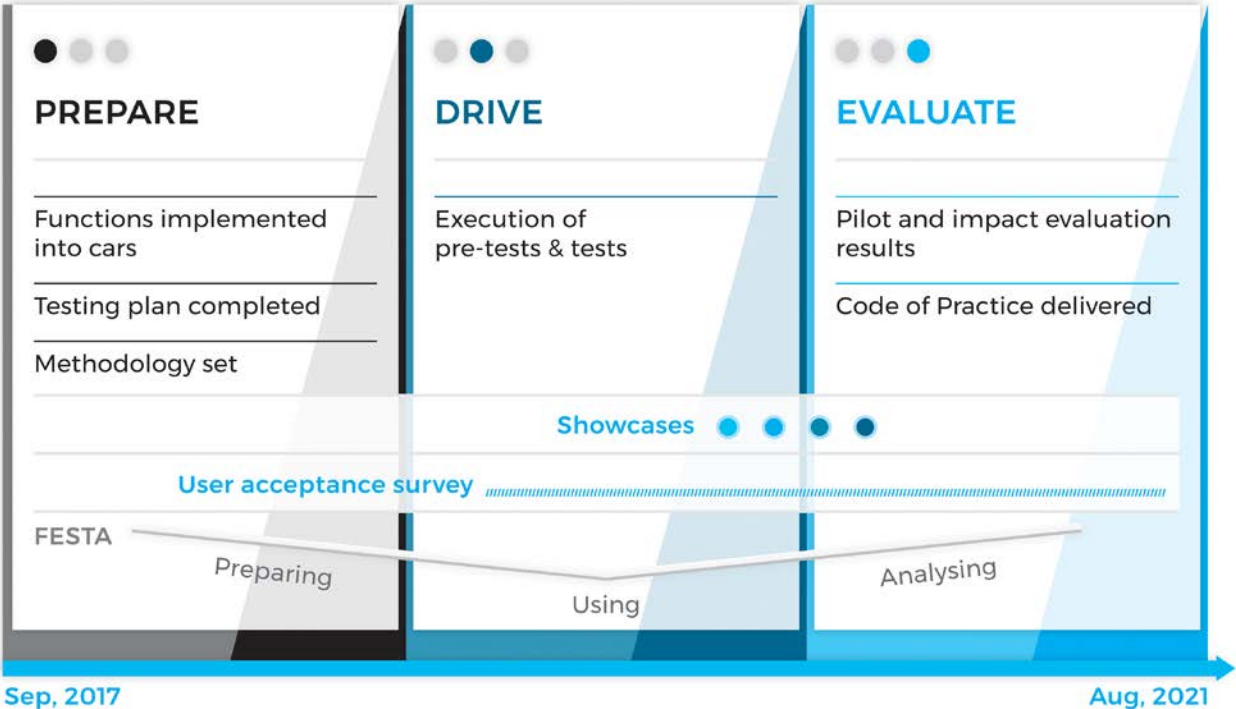


1,000 drivers

100 cars

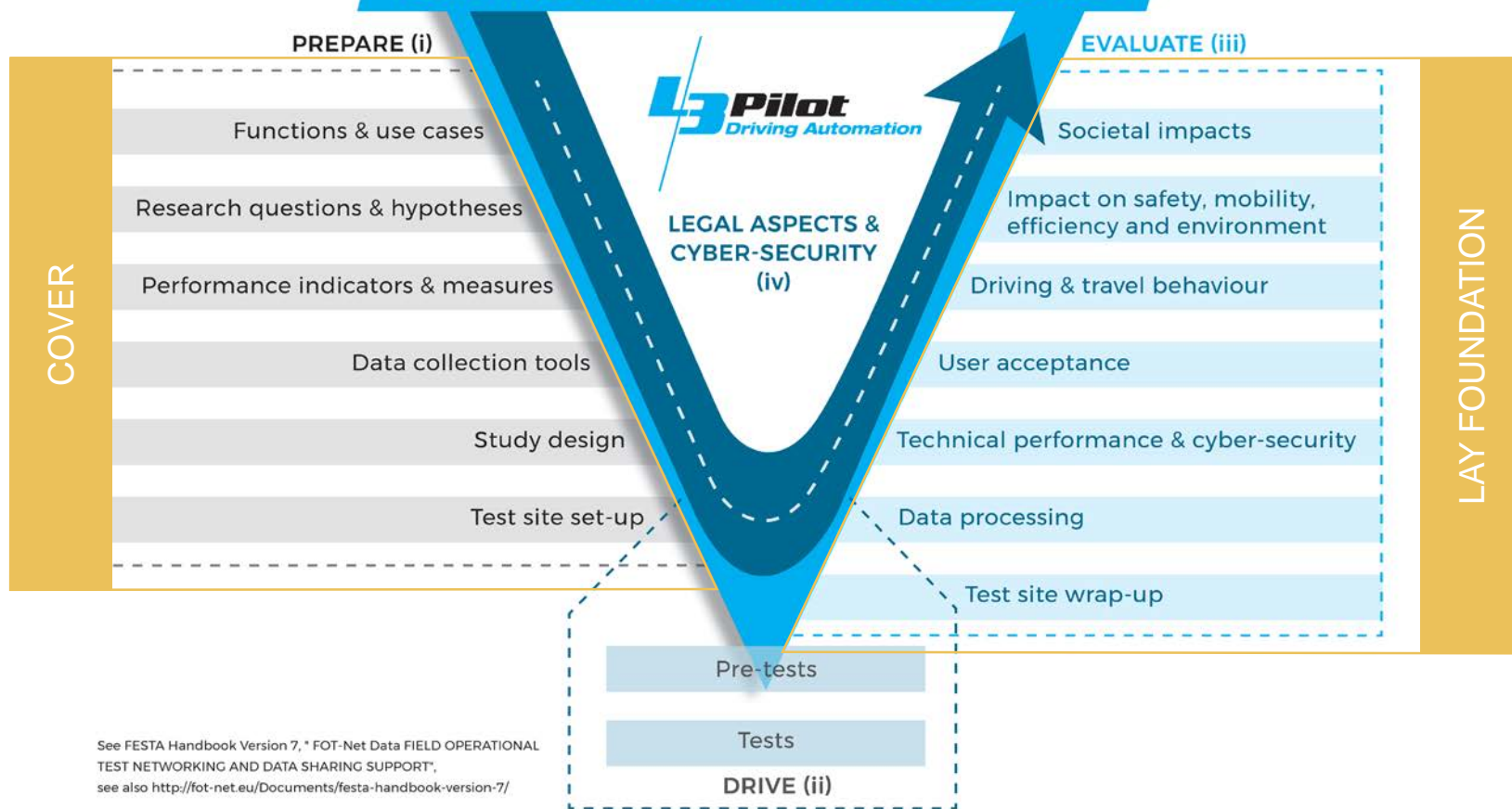
10 European countries

# Timeline





# FESTA Implementation Plan adapted to L3PILOT



See FESTA Handbook Version 7, "FOT-Net Data FIELD OPERATIONAL TEST NETWORKING AND DATA SHARING SUPPORT", see also <http://fot-net.eu/Documents/festa-handbook-version-7/>

## Outcome Methodology

Expected

### **Report D3.1 From research questions to logging requirements**

Process for data collection

2018

### **Report D3.2 Experimental procedure**

Detailed testing plan

2019

### **Report D3.3 Evaluation methods**

Evaluation plan for automated driving impacts

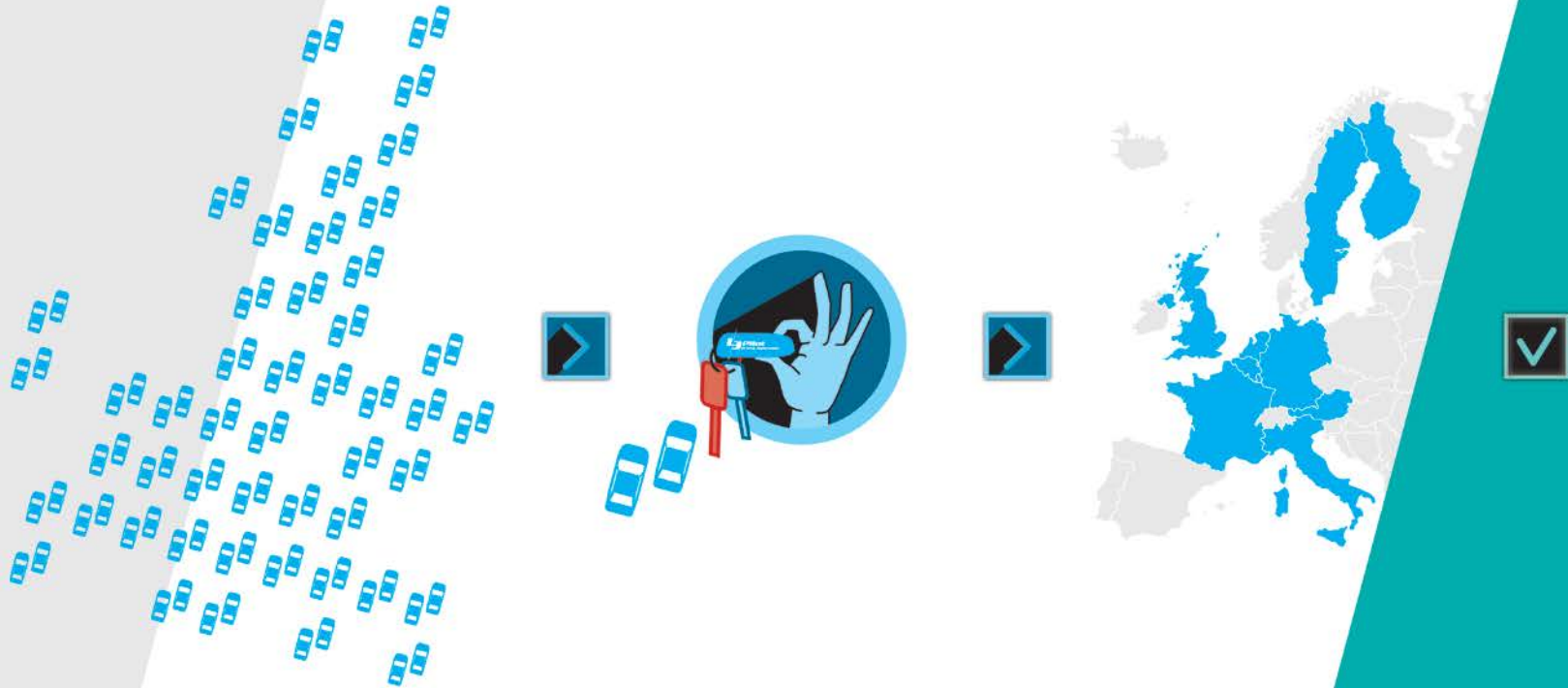
2019

### **Report D3.4 Evaluation plan**

Detailed evaluation procedures

2020

# The Cars are ready for Pilot.





## Outcome Fleet

Expected

**Report D4.1 Description and taxonomy of automated driving functions**

Automated driving functions detailed

2018

**Report D4.2 Legal requirements to automated driving piloting**

Legal constraints and requirements

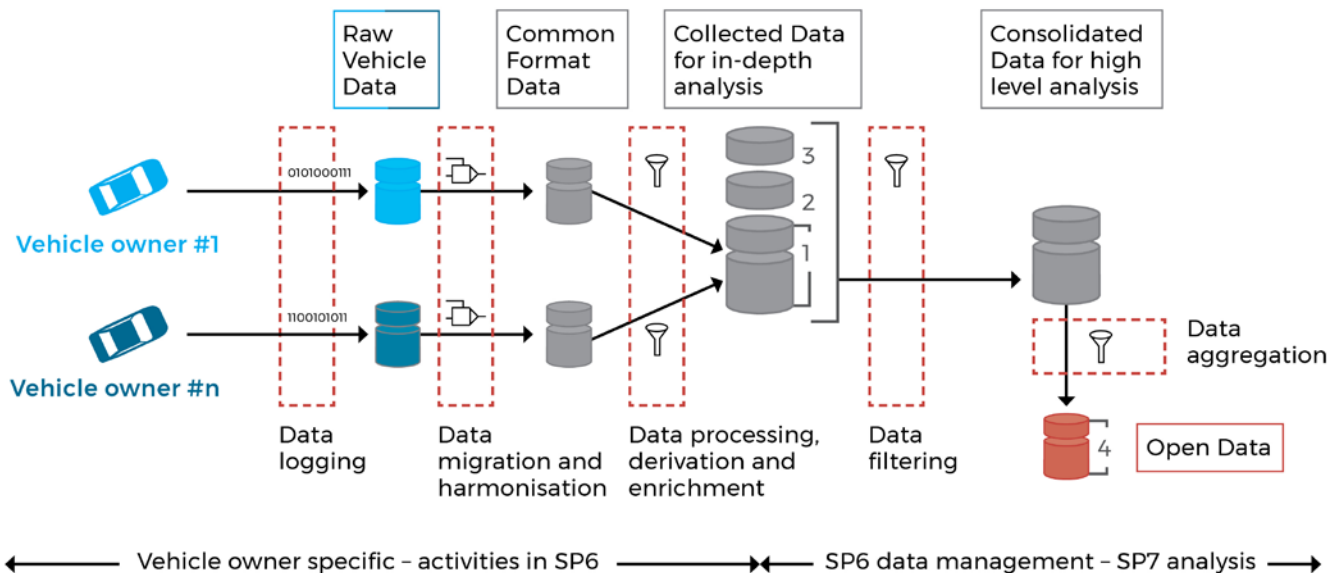
2019

**Report D4.3 Summary**

Summary of the work of the sub-project *Fleet*

2021

# Expected Data Flow



## Categories of data:

- 1 Derived Vehicle Data (CAN, GPS, Pls, video, and/or video annotations)
- 2 Subjective Data (interviews, questionnaires, simulator studies)
- 3 External Data (weather, map, infrastructure, other traffic participants, ...)
- 4 Open Data (aggregated data)

  Tools provided by SP5

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# Outcome Data

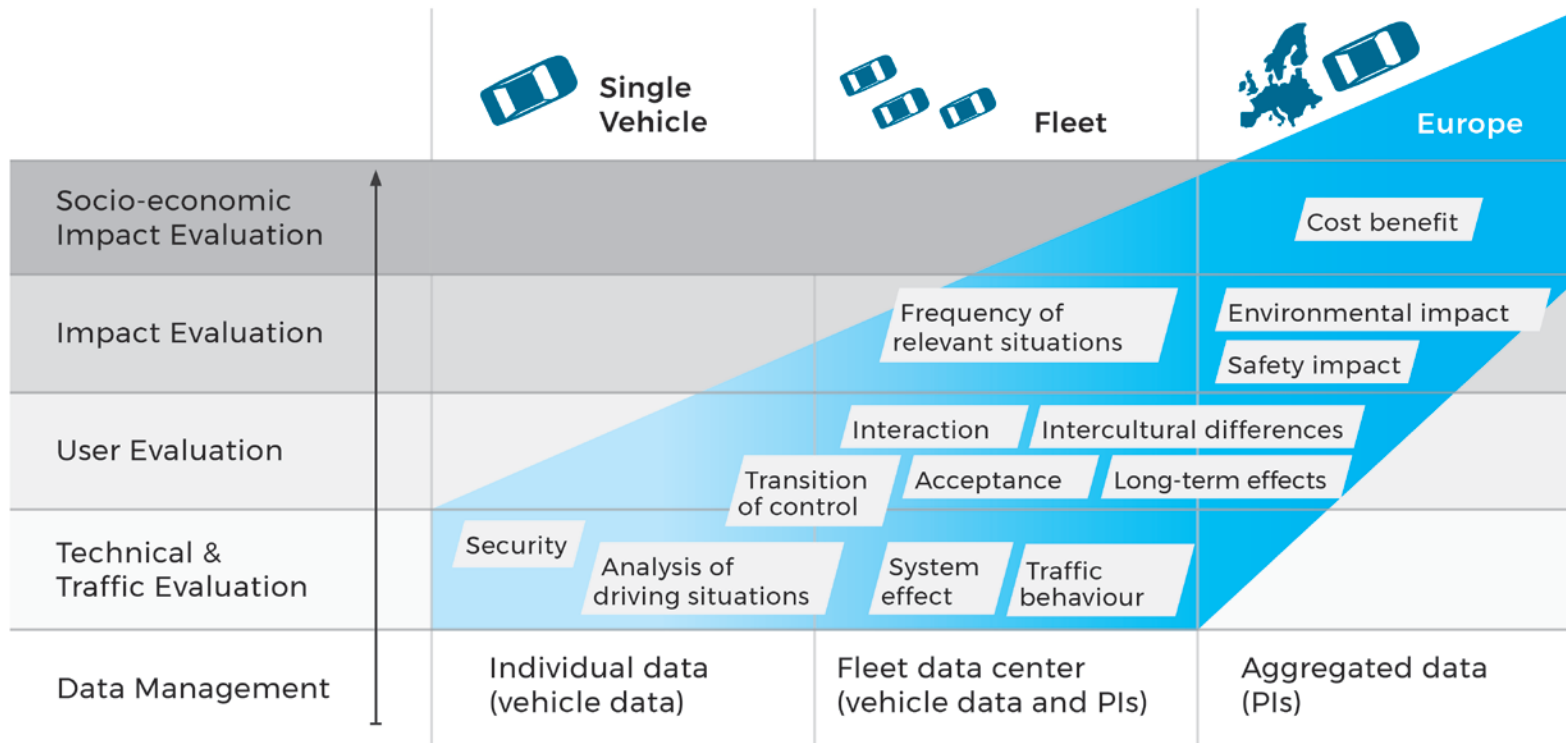
Expected

## Report D5.2 Guidelines and lessons learned

Set of guidelines and lessons learned about data logging, storage and management

2021

# Evaluation



## Outcome Evaluation

Expected

**Report D7.1 Annual quantitative survey about user acceptance towards Advanced Driver Assistance Systems (ADAS) and vehicle automation**  
Survey will provide longitudinal quantitative data

2019 – 2021

**Report D7.2 L3/L4 long-term study about user experience**  
Results of the long-term study about user experience

2019

**Report D7.3 Pilot evaluation results**  
Results on technical, traffic and user evaluation

2021

**Report D7.4 Impact evaluation results**  
Impact of the automated driving function concerning traffic safety, emissions and traffic flow

2021



# Code of Practice

Objective to provide a comprehensive guideline with best practices for the development of functions: **Code of Practice** for automated driving.

- Collect best practices on relevant topics.
- Describe a typical process for an automated driving function.
- Include hands-on checklists.
- Include safety aspects and methods to confirm a safe operation of automated driving functions.



Thank you for your kind attention.

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