





Aria Etemad, Volkswagen Group Innovation, L3Pilot Coordinator

"Automated driving technology has matured over the past ten years to a state in which road tests are required to answer key questions before the systems are introduced to the market. In the European research project L3Pilot, we are testing the viability of automated driving as a safe and efficient means of transportation. We will pave the way for large-scale field operational tests (FOTs) of automated in-vehicle functions."

In L3Pilot, we subject the functionality of automated driving systems to variable conditions in ten European countries, including cross-border routes. The technologies being tested cover a wide range of driving situations, such as parking, overtaking on motorways and driving through urban intersections. We cover the entire range of impact assessments, from the direct effects on driver behaviour to even the socio-economic impacts.

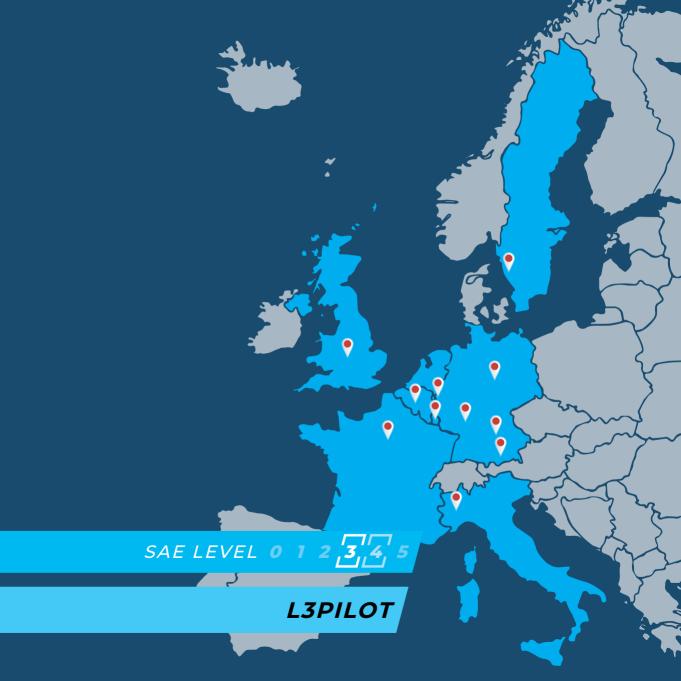
By the end of L3Pilot, we will have harmonised the various test sites as regards compliance with automated driving testing, thus creating a European-wide testing environment. To keep user desires in focus, we will collect data on user acceptance of vehicle automation in an annually published survey. Finally, involving various stakeholders we will explore the trends and commercialisation potentials related to the L3Pilot functions.

1,000 drivers

100 passenger cars

10 countries

ıntries	Partner	Countr	y Region	
	Volkswagen	DE	Hamburg, Wo	olfsburg
	Aptiv	DE, LU, FR	cross-border a	ctivities
A	UDI	DE	/ Ingolstadt, Necl	karsulm
BN	1W / [DE /	Munich	
CRF	· / IT		Turin	
FEV	DE	/ A	Aachen, Cologne	
Ford	DE, E	BE, UK / cr	oss-border activitie	es
Honda	DE	/ Fra	nkfurt am Main	
ika	DE	Aach	nen	
JLR	UK	Cover	ntry	
PSA	FR, DE	cross-k	order activities	
Renault	FR	Paris an	d other regions	,
Toyota	BE	Brussels		
Volvo Cars	SE	Gothenbu	rg	





Facts

Research budget of €68 million, €36 million of which has been co-funded by the European Commission

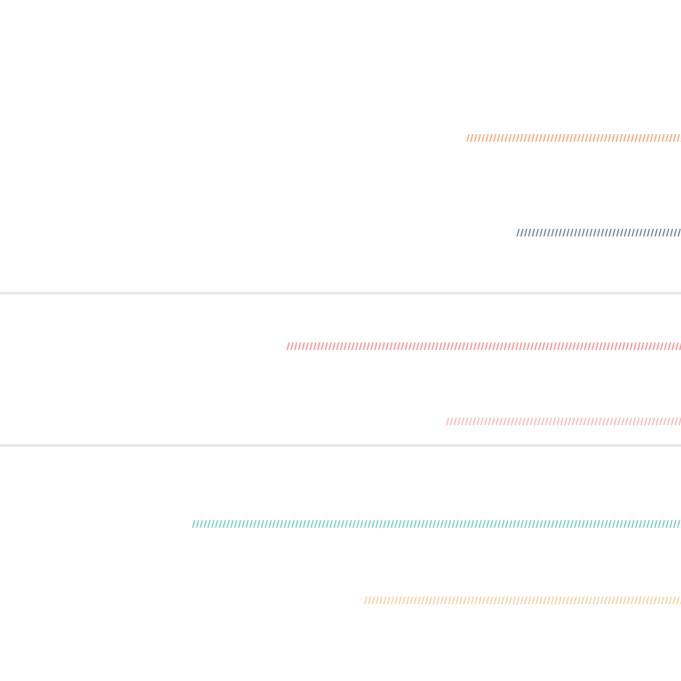
Coordinated by Aria Etemad,
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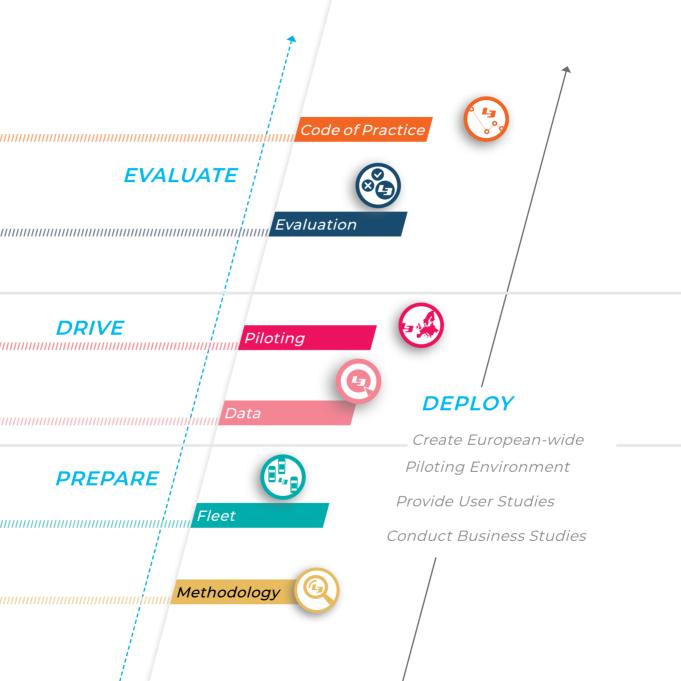
Duration of 4 years September 1, 2017 – August 31, 2021

Consortium includes 34 partners from 12 countries – Austria, Belgium, France, Finland, Germany, Greece, Italy, Netherlands, Norway, Sweden, Switzerland, UK; including 13 OEMs, 3 suppliers, 12 research institutes and universities, 2 insurers, 1 authority, 1 user group, and 2 SMEs.

There will be a series of L3Pilot showcases throughout the project`s duration. Learn more and follow us on Twitter, LinkedIn and on our website.

Twitter @_L3Pilot_ LinkedIn L3Pilot www.L3Pilot.eu







Providing a Comprehensive Methodology

Before beginning testing, we will set up a comprehensive methodology for piloting, evaluating and testing automated in-vehicle functions. We take on the user's point of view according to the project's user-centric approach. Describing the functions, we create a **FESTA Implementation Pla** solid foundation for PREPARE (i) setting up the research hypotheses and logging Functions & use cases requirements as well Research questions & hypotheses as for developing the experimental Performance indicators & measures procedures. For the Data collection tools overall methodology we refer to FESTA* Study design

and have modified it to better match the project`s objectives.

* See FESTA Handbook Version 7, FOT-Net Data FIELD OPERATIONAL

> see also http:// fot-net.eu/Documents/ festa-handbook-

> > version-7/

Test site set-up

Tests

Pre-tes

LEGAL ASF CYBER-SE

(iv)

PHASE I PREPARING THE PILOT



Preparing the Cars for the Pilot

Another task in the run-up to the testing is to provide a taxonomy and description of the fleet`s automated driving functions to be evaluated. We adapt, implement and pre-test the functions in the pilot fleet vehicles. In doing so we also consider legal issues such as compliance with laws and regulations, including data privacy and insurance.

Securing Automated Driving

Automated driving needs to be protected against multiple attack vectors such as hacking, tampering and misuse of the system, both inside vehicles as well as in remote parts of the car ecosystem. We assess a wide variety of cyberattacks in a controlled simulation environment.

L3PILOT APPLICATIONS

TRAFFIC JAM MOTORWAY PARKING

TRAFFIC JAM CHAUFFEUR MOTORWAY PILOT

MOTORWAY PILOT

PARKING PILOT

URBAN AREA

URBAN CHAUFFEUR
PARKING PILOT

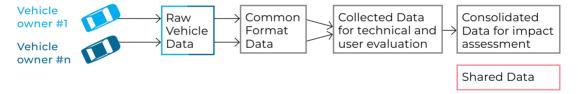
SAE LEVEL 0 1 2 3 4 5



Developing Data Management Tools

All data-related activities will be supported by a set of tools that we develop for the pilot purposes. We define data logger requirements and provide the appropriate data loggers. Working together we develop data formats for analysing and describing L3Pilot data, work on the correct strategy for data storage, and flesh out the needed data processing tools. The guidelines and lessons learned about data logging, storage and management will be made available after the project.

Expected Data Flow



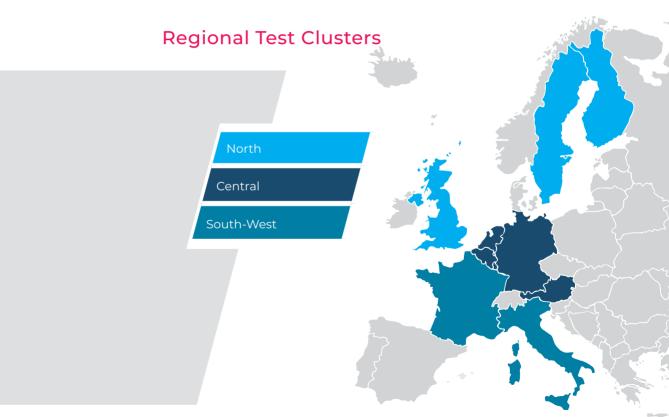
Data Categories

We distinguish between four categories of data produced in L3Pilot research: 1 derived vehicle data from controller area network, GPS, sensors, performance indicators and video annotations; 2 subjective data from interviews, questionnaires and simulator studies; 3 external data such as weather, map and; 4 shared data.



Carrying out Pilot Tests

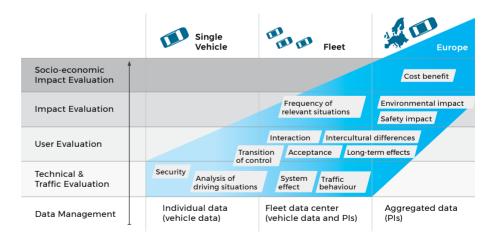
We coordinate and harmonise our testing activities to meet the challenges of executing a pilot across ten European countries, including cross-border activities. The testing is monitored: we ensure that data delivery is properly handled by data owners, by the project and as regards data verification rules that have been agreed upon.





Evaluating Results

After having collected the pilot data, we will analyse it and draw conclusions on technical aspects, user acceptance, driving and travel behaviour, and the impact on traffic and safety. We assess long-term effects of automated driving on user –attitudes and acceptance as well as the readiness and reliability of automated driving functions. We determine the safety, efficiency, mobility and economic impact of automated driving applications under mixed automated traffic conditions based on real-world pilot data and further develop simulation tools. Furthermore, we will provide a cost-benefit analysis with respect to Europe as a whole.





Providing a Code of Practice for Automated Driving

We will collect best practices on developing automated driving functions and compile them into a Code of Practice. In this, we will describe a typical process for developing automated driving functions, including hands-on checklists and safety aspects as well as methods to confirm the safe operation of automated driving functions.

Best practices will be provided for three development phases of automated driving functions:

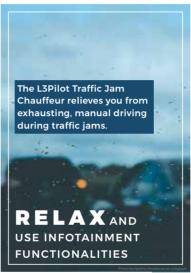
Definition and concept

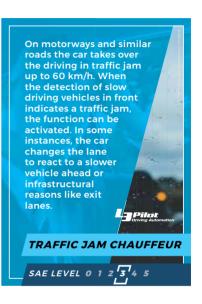
Design, verification

During customer operation

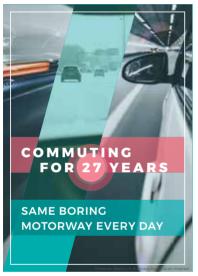
L3PILOT APPLICATION TRAFFIC JAM CHAUFFEUR







L3PILOT APPLICATION MOTORWAY CHAUFFEUR

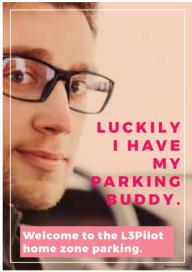






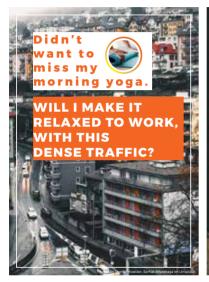
L3PILOT APPLICATION PARKING CHAUFFEUR



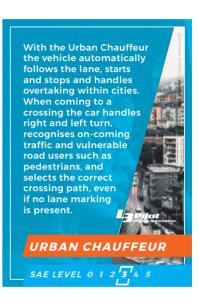




3PILOT APPLICATION URBAN CHAUFFEUR







Partners











































































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European Council for Automotive R&D EUCAR.